



TQMa6ULx Preliminary User's Manual

TQMa6ULx UM 0001
27.08.2016

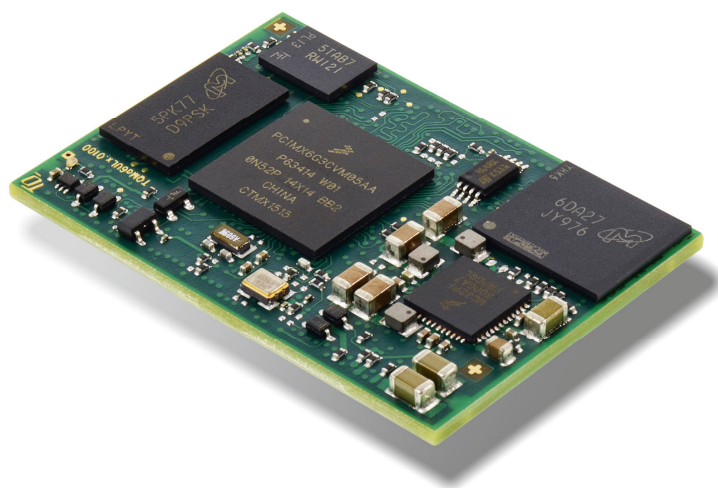




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1. ABOUT THIS MANUAL

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1.4 Imprint

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1.5 Tips on safety

Improper or incorrect handling of the product can substantially reduce its life span.

1.6 Symbols and typographic conventions

Table 1: Terms and conventions

Symbol	Meaning
	This symbol represents the handling of electrostatic-sensitive modules and / or components. These components are often damaged / destroyed by the transmission of a voltage higher than about 50 V. A human body usually only experiences electrostatic discharges above approximately 3,000 V.
	This symbol indicates the possible use of voltages higher than 24 V. Please note the relevant statutory regulations in this regard. Non-compliance with these regulations can lead to serious damage to your health and may damage or destroy the component.
	This symbol indicates a possible source of danger. Ignoring the instructions described can cause health damage, or damage the hardware.
	This symbol represents important details or aspects for working with TQ-products.
Command	A font with fixed-width is used to denote commands, contents, file names, or menu items.

1.7 Handling and ESD tips

General handling of your TQ-products

	<p>The TQ-product may only be used and serviced by certified personnel who have taken note of the information, the safety regulations in this document and all related rules and regulations.</p> <p>A general rule is not to touch the TQ-product during operation. This is especially important when switching on, changing jumper settings or connecting other devices without ensuring beforehand that the power supply of the system has been switched off.</p> <p>Violation of this guideline may result in damage / destruction of the TQMa6ULx and be dangerous to your health.</p> <p>Improper handling of your TQ-product would render the guarantee invalid.</p>
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Proper ESD handling

	<p>The electronic components of your TQ-product are sensitive to electrostatic discharge (ESD).</p> <p>Always wear antistatic clothing, use ESD-safe tools, packing materials etc., and operate your TQ-product in an ESD-safe environment. Especially when you switch modules on, change jumper settings, or connect other devices.</p>
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1.8 Naming of signals

A hash mark (#) at the end of the signal name indicates a low-active signal.

Example: RESET#

If a signal can switch between two functions and if this is noted in the name of the signal, the low-active function is marked with a hash mark and shown at the end.

Example: C / D#

If a signal has multiple functions, the individual functions are separated by slashes when they are important for the wiring. The identification of the individual functions follows the above conventions.

Example: WE2# / OE#

1.9 Further applicable documents / presumed knowledge

- **Specifications and manual of the modules used:**
These documents describe the service, functionality and special characteristics of the module used (incl. BIOS).
- **Specifications of the components used:**
The manufacturer's specifications of the components used, for example CompactFlash cards, are to be taken note of. They contain, if applicable, additional information that must be taken note of for safe and reliable operation. These documents are stored at TQ-Systems GmbH.
- **Chip errata:**
It is the user's responsibility to make sure all errata published by the manufacturer of each component are taken note of. The manufacturer's advice should be followed.
- **Software behaviour:**
No warranty can be given, nor responsibility taken for any unexpected software behaviour due to deficient components.
- **General expertise:**
Expertise in electrical engineering / computer engineering is required for the installation and the use of the device.

The following documents are required to fully comprehend the following contents:

- Circuit diagram MBa6ULx
- CPU Reference Manual IMX6ULxRM
- Preliminary User's Manual MBa6ULx
- Documentation of boot loader U-Boot (<http://www.denx.de/wiki/U-Boot/Documentation>)
- Documentation of PTXdist (<http://www.ptxdist.de>)

2. BRIEF DESCRIPTION

This Preliminary User's Manual describes the TQMa6ULx and refers to some software settings.

A certain derivative of the TQMa6ULx does not necessarily provide all features described in this Preliminary User's Manual.

This Preliminary User's Manual does also not replace the NXP Reference Manual of the CPU (6).

The TQMa6ULx is a universal Minimodule based on the NXP ARM CPU MCIMX6G3CVM05 (i.MX6ULx).

The Cortex® A7 core of this CPU works typically with 528 MHz.¹

2.1 Block diagram i.MX6ULx CPU

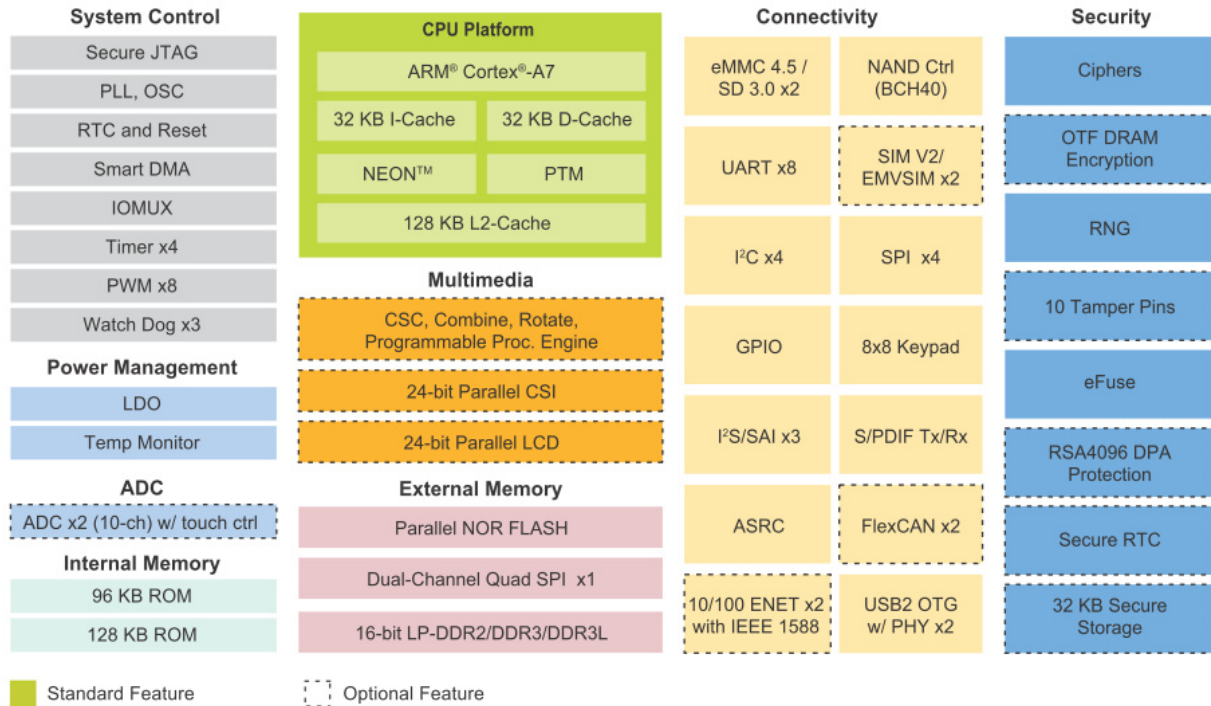


Illustration 1: Block diagram i.MX6ULx CPU
(Source: [NXP](#))

The TQMa6ULx extends the TQC product range and offers an outstanding computing performance. A suitable CPU derivative (UL1, UL2, and UL3) can be selected for each requirement.

All essential CPU pins are routed to the connectors.

There are therefore no restrictions for customers using the TQMa6ULx with respect to an integrated customised design.

All essential components like CPU, DDR3L SDRAM, eMMC and power management are already integrated on the TQMa6ULx.

The main features of the TQMa6ULx are:

- NXP i.MX6ULx CPU
- DDR3L SDRAM
- eMMC NAND flash / QSPI NOR flash
- 64 kbit EEPROM / temperature sensor
- NXP Power Management Integrated Circuit PF3000
- All essential CPU pins of the TQMa6ULx are routed to the connectors
- Extended temperature range
- Single supply voltage 5 V

The MBa6ULx serves as an evaluation board for the TQMa6ULx.

1: On selected qualifications up to 700 MHz.



2.2 Key functions and characteristics

The following components are implemented on the TQMa6ULx:

- i.MX6ULx CPU
- DDR3L SDRAM
- eMMC NAND flash
- QSPI NOR flash
- EEPROM
- Temperature sensor
- Supervisor with Reset structure
- Power supply by PMIC with Power Sequencing
- 2 Connectors (200 pins)

The following interfaces are provided at the connectors of the TQMa6ULx²:

- 2 × Ethernet 10/100 RMII
- 2 × I²C (1 × for the devices on the TQMa6ULx)
- 1 × JTAG
- 1 × Parallel LCD RGB 24-bit interface
- 2 × CAN
- 2 × I²C
- 1 × SPI
- 2 × USB 2.0 OTG
- 11 × GPIO
- 3 × UART (with handshake)
- 1 × SD 4-bit (SDIO / MMC / SD card)
- 10 × Tamper
- 1 × differential clock (CCM)
- 1 × QSPI (for second SPI NOR flash; SS1)

By adapting the pin configuration, further interfaces of the i.MX6ULx are also available as an alternative to the mentioned factory configuration. These are amongst other:

- Camera Sensor-Interfaces 8-bit (CSI – CMOS Sensor Interface)
- Synchronous Audio Interface (SAI – e.g., I²S)
- PWM
- ADC
- Enhanced Periodic Interrupt Timer
- General Purpose Media Interface
- General Purpose Timer
- Keypad Port
- More audio interfaces
- One more I²C interface
- More SPI interfaces
- More UARTs

2: Number of interfaces depends on the i.MX6ULx derivative.

3. ELECTRONICS

The information in this Preliminary User's Manual is only valid in connection with the boot loader adapted for the TQMa6ULx, which is preinstalled on every TQMa6ULx (see also section 5) and the BSP provided by TQ-Systems GmbH.

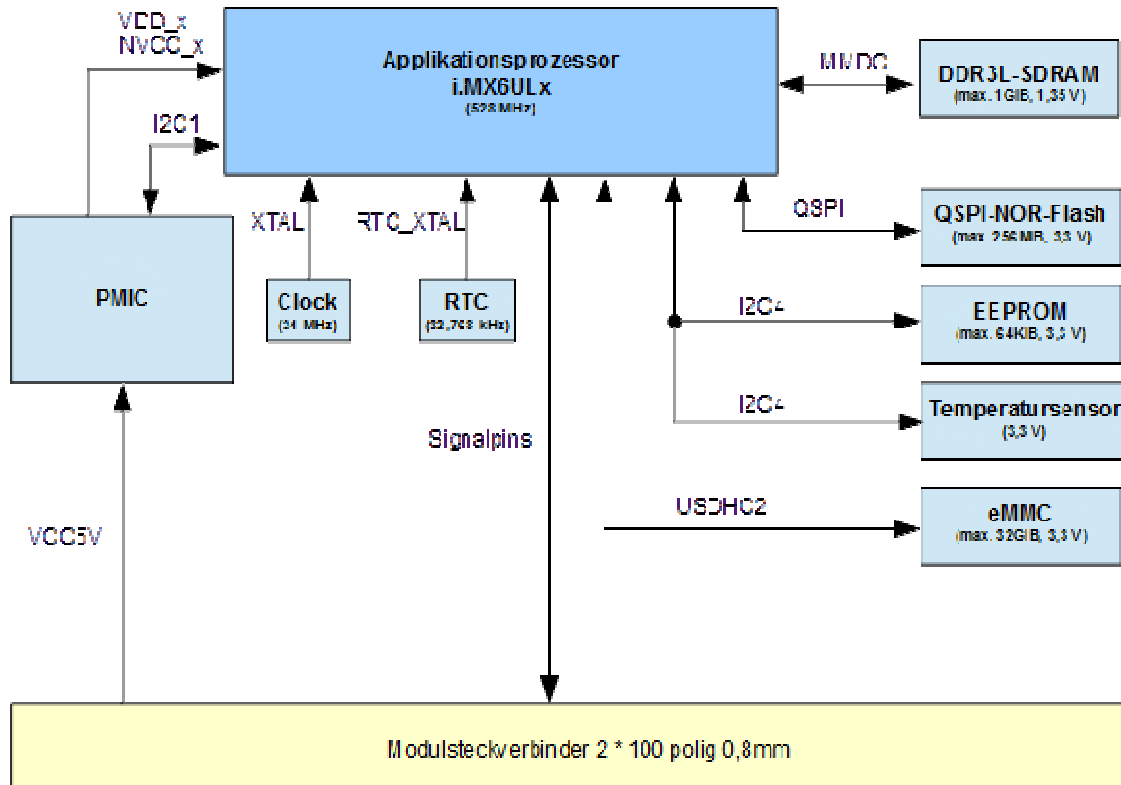


Illustration 2: Block diagram TQMa6ULx (simplified)


3.1 Interfaces to other systems and devices

3.1.1 Pin multiplexing

When using the processor signals, the multiple pin configurations by different processor-internal function units must be taken note of. The pin assignment listed in Table 2 and Table 3 refer to the corresponding standard TQ-BSP of TQ-Systems GmbH in combination with the Starterkit MBa6ULx.

NXP provides a tool showing the multiplexing and simplifies the selection and configuration (i.MX Pins Tool – NXP Tool).

The electrical and pin characteristics are to be taken from the Data Sheets of the CPU (1), (2), (5), the Reference Manual of the CPU (6), and the Data Sheet of the PMIC (7).

Attention: Destruction or malfunction	
	<p>Depending on the configuration, many of the CPU pins can provide several different functions. Please take note of the information concerning the configuration of these pins in the i.MX6ULx Reference Manual (6), before integration or start-up of your carrier board / Starterkit.</p> <p>Improper programming by operating software can cause malfunctions, deterioration or destruction of the TQMa6ULx.</p>



3.1.1.1 Connector X1

Table 2: Pinout connector X1

CPU ball	I/O	Level	Group	Signal	Pin	Signal	Group	Level	I/O	CPU ball
-	P	5 V	Power	VCC5V	1	2	VCC5V	5 V	P	-
-	P	5 V	Power	VCC5V	3	4	VCC5V	5 V	P	-
-	P	5 V	Power	VCC5V	5	6	VCC5V	5 V	P	-
-	P	0 V	Ground	DGND	7	8	DGND	0 V	P	-
-	P	0 V	Ground	DGND	9	10	LICELL ³	3.3 V	P	-
-	P	1.8 V	Power	VCC1V8_OUT	11	12	DGND	0 V	P	-
-	P	0 V	Ground	DGND	13	14	VCC3V3_V33_OUT	3.3 V	P	-
-	P	3.0 V	Power	VSNVS_REF_OUT	15	16	DGND	0 V	P	-
-	P	3.3 V	Power	VCC3V3_REF_OUT	17	18	VCC2V5_OUT	2.5 V	P	-
-	P	0 V	Ground	DGND	19	20	DGND	0 V	P	-
-	P	0.675 V	Power	VCCDDR_OUT	21	22	VCCCORE_OUT	1.4 V	P	-
-	P	0 V	Ground	DGND	23	24	DGND	0 V	P	-
F4	P	1.8 / 3.3 V ⁴	Power	NVCC_CSI	25	26	NVCC_ENET	2.5 / 3.3 V ⁵	P	F13
-	P	0 V	Ground	DGND	27	28	DGND	0 V	P	-
P17	O	2.5 V	CCM	CCM_CLK1_P	29	30	DGND	0 V	P	-
P16	O	2.5 V	CCM	CCM_CLK1_N	31	32	DGND	0 V	P	-
-	P	0 V	Ground	DGND	33	34	DGND	0 V	P	-
R8	I	3.3 V	Config	MX6ULx_ONOFF	35	36	USB_OTG2_OC	3.3 V	I	L17
T9	I	3.3 V	Config	PMIC_PWRON	37	38	USB_OTG2_PWR	3.3 V	O	L14
-	P	0 V	Ground	DGND	39	40	DGND	0 V	P	-
U16	O	Open-Drain	USB	USB_OTG1_CHD#	41	42	USB_OTG2_VBUS	5 V	P	U12
-	P	0 V	Ground	DGND	43	44	USB_OTG2_ID	3.3 V	I	M17
T12	P	5 V	Power	USB_OTG1_VBUS	45	46	DGND	0 V	P	-
K13	I	3.3 V	USB	USB_OTG1_ID	47	48	USB_OTG2_DN	3 V	I/O	T13
L15	I	3.3 V	USB	USB_OTG1_OC	49	50	USB_OTG2_DP	3 V	I/O	U13
M16	O	3.3 V	USB	USB_OTG1_PWR	51	52	DGND	0 V	P	-
-	P	0 V	Ground	DGND	53	54	UART3_RX_DATA	3.3 V	I	H16
T15	I/O	3 V	USB	USB_OTG1_DN	55	56	UART3_TX_DATA	3.3 V	O	H17
U15	I/O	3 V	USB	USB_OTG1_DP	57	58	DGND	0 V	P	-
-	P	0 V	Ground	DGND	59	60	BOOT_MODE0	3.0 V ⁶	I	T10
N8	I	3.3 V	SNVS	SNVS_TAMPER5	61	62	BOOT_MODE1	3.0 V ⁶	I	U10
N11	I	3.3 V	SNVS	SNVS_TAMPER6	63	64	DGND	0 V	P	-
N10	I	3.3 V	SNVS	SNVS_TAMPER7	65	66	SNVS_TAMPER0	3.3 V	I	R10
N9	I	3.3 V	SNVS	SNVS_TAMPER8	67	68	SNVS_TAMPER1	3.3 V	I	R9
R6	I	3.3 V	SNVS	SNVS_TAMPER9	69	70	SNVS_TAMPER2	3.3 V	I	P11
-	P	0 V	Ground	DGND	71	72	SNVS_TAMPER3	3.3 V	I	P10
M14	I	3.3 V	JTAG	JTAG_TCK	73	74	SNVS_TAMPER4	3.3 V	I	P9
P14	I	3.3 V	JTAG	JTAG_TMS	75	76	DGND	0 V	P	-
N16	I	3.3 V	JTAG	JTAG_TDI	77	78	JTAG_TDO	3.3 V	O	N15
-	P	0 V	Ground	DGND	79	80	JTAG_TRST#	3.3 V	I	N14
M15	I/O	3.3 V	GPIO	GPIO1_IO09	81	82	JTAG_MOD	3.3 V	I	P15
K15	I/O	3.3 V	GPIO	GPIO1_IO18	83	84	DGND	0 V	P	-
J14	I/O	3.3 V	GPIO	GPIO1_IO19	85	86	UART1_RX_DATA	3.3 V	I	K16
J16		3.3 V	I ² C	I2C4_SDA	87	88	UART1_TX_DATA	3.3 V	O	K14
J17		3.3 V	I ² C	I2C4_SCL	89	90	DGND	0 V	P	-
-	P	0 V	Ground	DGND	91	92	CAN2_RX	3.3 V	I	H14
-	I	-	RFU	RFU1	93	94	CAN2_TX	3.3 V	O	J15
P8	I	3.3 V	Config	RESET_IN#	95	96	CAN1_RX	3.3 V	I	G14
-	O	3.3 V	Config	RESET_OUT#	97	98	CAN1_TX	3.3 V	O	H15
-	P	0 V	Ground	DGND	99	100	DGND	0 V	P	-

3: LICELL can be left open, if RTC backup or other functions of the SNVS domain are not required (see NXP documentation).
 4: 1.8 V, if NVCC_CSI is connected to VCC1V8_OUT. 3.3 V, if NVCC_CSI is connected to VCC3V3_V33_OUT.
 5: 2.5 V, if NVCC_ENET is connected to VCC2V5_OUT. 3.3 V, if NVCC_ENET is connected to VCC3V3_REF_OUT.
 6: Use VSNVS_REF_OUT as reference voltage for BOOT-CFG resistors.



3.1.1.2 Connector X2

Table 3: Pinout connector X2

CPU ball	I/O	Level	Group	Signal	Pin	Signal	Group	Level	I/O	CPU ball	
-	P	0 V	Ground	DGND	1	2	DGND	Ground	0 V	P	-
G16	O	3.3 V	SPI	SPI2_SS0#	3	4	SPI2_MISO	SPI	3.3 V	I	G13
G17	O	3.3 V	SPI	SPI2_SCLK	5	6	SPI2_MOSI	SPI	3.3 V	O	F17
F15	O	2.5 / 3.3 V ⁷	ENET	ENET1_TX_EN	7	8	DGND	Ground	0 V	P	-
F14	O	2.5 / 3.3 V ⁷	ENET	ENET1_TX_CLK	9	10	ENET_MGMT_MDC	ENET	2.5 / 3.3 V ⁷	O	L16
-	P	0 V	Ground	DGND	11	12	ENET_MGMT_MDIO	ENET	2.5 / 3.3 V ⁷	I/O	K17
E15	O	2.5 / 3.3 V ⁷	ENET	ENET1_TDATA0	13	14	ENET2_TX_CLK	ENET	2.5 / 3.3 V ⁷	O	D17
E14	O	2.5 / 3.3 V ⁷	ENET	ENET1_TDATA1	15	16	DGND	Ground	0 V	P	-
F16	I	2.5 / 3.3 V ⁷	ENET	ENET1_RDATA0	17	18	ENET2_RX_ER	ENET	2.5 / 3.3 V ⁷	I	D16
E17	I	2.5 / 3.3 V ⁷	ENET	ENET1_RDATA1	19	20	ENET2_RDATA1	ENET	2.5 / 3.3 V ⁷	I	C16
E16	I	2.5 / 3.3 V ⁷	ENET	ENET1_RX_EN	21	22	ENET2_RDATA0	ENET	2.5 / 3.3 V ⁷	I	C17
D15	I	2.5 / 3.3 V ⁷	ENET	ENET1_RX_ER	23	24	ENET2_RX_EN	ENET	2.5 / 3.3 V ⁷	I	B17
-	P	0 V	Ground	DGND	25	26	ENET2_TX_EN	ENET	2.5 / 3.3 V ⁷	O	B15
B16	I/O	3.3 V ⁸	LCD	LCD_DATA23	27	28	ENET2_TDATA0	ENET	2.5 / 3.3 V ⁷	O	A15
A14	I/O	3.3 V ⁸	LCD	LCD_DATA22	29	30	ENET2_TDATA1	ENET	2.5 / 3.3 V ⁷	O	A16
B14	I/O	3.3 V ⁸	LCD	LCD_DATA21	31	32	DGND	Ground	0 V	P	-
C14	I/O	3.3 V ⁸	LCD	LCD_DATA20	33	34	LCD_DATA15	LCD	3.3 V ⁸	I/O	D13
-	P	0 V	Ground	DGND	35	36	LCD_DATA14	LCD	3.3 V ⁸	I/O	A12
D14	I/O	3.3 V ⁸	LCD	LCD_DATA19	37	38	LCD_DATA13	LCD	3.3 V ⁸	I/O	B12
A13	I/O	3.3 V ⁸	LCD	LCD_DATA18	39	40	LCD_DATA12	LCD	3.3 V ⁸	I/O	C12
B13	I/O	3.3 V ⁸	LCD	LCD_DATA17	41	42	DGND	Ground	0 V	P	-
C13	I/O	3.3 V ⁸	LCD	LCD_DATA16	43	44	LCD_DATA11	LCD	3.3 V ⁸	I/O	D12
-	P	0 V	Ground	DGND	45	46	LCD_DATA10	LCD	3.3 V ⁸	I/O	E12
D11	I/O	3.3 V ⁸	LCD	LCD_DATA07	47	48	LCD_DATA09	LCD	3.3 V ⁸	I/O	A11
A10	I/O	3.3 V ⁸	LCD	LCD_DATA06	49	50	LCD_DATA08	LCD	3.3 V ⁸	I/O	B11
B10	I/O	3.3 V ⁸	LCD	LCD_DATA05	51	52	DGND	Ground	0 V	P	-
C10	I/O	3.3 V ⁸	LCD	LCD_DATA04	53	54	LCD_CLK	LCD	3.3 V ⁸	O	A8
-	P	0 V	Ground	DGND	55	56	DGND	Ground	0 V	P	-
D10	I/O	3.3 V ⁸	LCD	LCD_DATA03	57	58	LCD_ENABLE	LCD	3.3 V ⁸	O	B8
E10	I/O	3.3 V ⁸	LCD	LCD_DATA02	59	60	LCD_RESET	LCD	3.3 V ⁸	O	E9
A9	I/O	3.3 V ⁸	LCD	LCD_DATA01	61	62	LCD_HSYNC	LCD	3.3 V ⁸	O	D9
B9	I/O	3.3 V ⁸	LCD	LCD_DATA00	63	64	LCD_VSYNC	LCD	3.3 V ⁸	I/O	C9
-	P	0 V	Ground	DGND	65	66	QSPI_A_DATA0	QSPI	3.3 V	I/O	A3
B3	I/O	3.3 V	SD	SD1_DATA0	67	68	QSPI_A_DATA1	QSPI	3.3 V	I/O	C5
B2	I/O	3.3 V	SD	SD1_DATA1	69	70	QSPI_A_DATA2	QSPI	3.3 V	I/O	B5
B1	I/O	3.3 V	SD	SD1_DATA2	71	72	QSPI_A_DATA3	QSPI	3.3 V	I/O	A4
A2	I/O	3.3 V	SD	SD1_DATA3	73	74	QSPI_A_SS1#	QSPI	3.3 V	O	A5
C2	I/O	3.3 V	SD	SD1_CMD	75	76	DGND	Ground	0 V	P	-
-	P	0 V	Ground	DGND	77	78	QSPI_A_SCK	QSPI	3.3 V	O	D5
C1	O	3.3 V	SD	SD1_CLK	79	80	DGND	Ground	0 V	P	-
-	P	0 V	Ground	DGND	81	82	RFU2	RFU	-	I	-
E4	I/O	3.3 V ⁹	GPIO	GPIO4_IO21	83	84	DGND	Ground	0 V	P	-
E3	I/O	1.8 / 3.3 V ⁹	GPIO	GPIO4_IO22	85	86	GPIO4_IO25	GPIO	1.8 / 3.3 V ⁹	I/O	D4
-	P	0 V	Ground	DGND	87	88	GPIO4_IO26	GPIO	1.8 / 3.3 V ⁹	I/O	D3
E2	I/O	1.8 / 3.3 V ⁹	GPIO	GPIO4_IO23	89	90	GPIO4_IO27	GPIO	1.8 / 3.3 V ⁹	I/O	D2
E1	I/O	1.8 / 3.3 V ⁹	GPIO	GPIO4_IO24	91	92	GPIO4_IO28	GPIO	1.8 / 3.3 V ⁹	I/O	D1
-	I	-	RFU	RFU3	93	94	DGND	Ground	0 V	P	-
F3	O	3.3 V	I ² C	I2C2_SCL	95	96	UART6_RX_DATA	UART	3.3 V	I	E5
F2	I/O	3.3 V	I ² C	I2C2_SDA	97	98	UART6_TX_DATA	UART	3.3 V	O	F5
-	P	0 V	Ground	DGND	99	100	DGND	Ground	0 V	P	-

7: 2.5 V, if NVCC_ENET is connected to VCC2V5_OUT. 3.3 V, if NVCC_ENET is connected to VCC3V3_REF_OUT.
 8: Use VCC3V3_REF_OUT as reference voltage for BOOT-CFG resistors.
 9: 1.8 V, if NVCC_CSI is connected to VCC1V8_OUT. 3.3 V, if NVCC_CSI is connected to VCC3V3_V33_OUT.

3.2 System components

3.2.1 i.MX6ULx CPU


3.2.1.1 CPU derivatives

Depending on the derivative of the TQMa6ULx one of the following derivatives of the CPU is assembled:

Table 4: CPU derivatives

Description	CPU clock	Temperature	Supported by TQ-BSP
MCIMX6G1CVM05AA	528 MHz	-40 °C to +105 °C	Yes
MCIMX6G2CVM05AA	528 MHz	-40 °C to +105 °C	Yes
MCIMX6G3CVM05AA	528 MHz	-40 °C to +105 °C	Yes

3.2.1.2 CPU errata

Attention: Malfunction	
	Please take note of the current errata of the i.MX6ULx CPU (2).

3.2.1.3 Boot modes

The i.MX6ULx contains a ROM with integrated boot loader.

After power-up, the boot code initializes the hardware and then loads the program image from the selected boot device.

The eMMC or the QSPI NOR flash integrated on the TQMa6ULx can for example be selected as the standard boot device.

Additional boot interfaces are available as an alternative to booting from the integrated eMMC or the QSPI NOR flash, see 3.2.1.5.

More information about boot interfaces and its configuration is to be taken from the Data Sheet of the CPU (1) and the Reference Manual of the CPU (6).

The boot device and its configuration, as well as different CPU settings have to be set via different boot mode registers.

Therefore, the i.MX6ULx provides two possibilities:

- Burning internal eFuses
- Reading dedicated GPIO pins


The exact behaviour during booting depends on the value of the register BT_FUSE_SEL (default = 0).

The following table shows the behaviour of the bit BT_FUSE_SEL in dependence of the selected boot mode:

Table 5: Boot modes and BT_FUSE_SEL

BOOT_MODE[1:0]	Boot type	Setting BT_FUSE_SEL	Recommended for
00 (default)	Boot From Fuses	0 = Boot using Serial Loader (Default) 1 = Boot mode configuration is taken from fuses.	Series production
01	Serial Downloader	n/a	Development / production
10	Internal Boot	0 = Boot mode configuration is taken from GPIOs. (Default) 1 = Boot mode configuration is taken from fuses.	Development
11	Reserved	n/a	n/a

3.2.1.4 Boot configuration

Note: Boot configuration	
	QSPI NOR flash is set as boot device when the TQMa6ULx is delivered.

Some general settings are done with some eFuses independent from the boot device:

Table 6: General boot settings

Signal / eFuse	Pin name	Ball	Setting	Default	TQMa6ULx ¹⁰
BOOT_CFG1[7:0]	LCD_DATA[7:0]	–	Boot configuration 1: Specific to selected boot mode	–	000 1000
BOOT_CFG2[7:3] BOOT_CFG2[1:0]	LCD_DATA[15:11] LCD_DATA[9:8]	–	Boot configuration 2: Specific to selected boot mode	–	–
BOOT_CFG2[2]	LCD_DATA10	E12	Boot frequencies (ARM / DDR): 0 = 500 / 400 MHz 1 = 250 / 200 MHz	0	–
BOOT_CFG3[7:0]	–	–	Reserved	–	–
BOOT_CFG4[6:0]	–	–	Boot configuration 4: Specific to selected boot mode	–	–
BOOT_CFG4[7]	LCD_DATA23	B16	Debug loop: 0 = Loop disabled 1 = Loop enabled	0	–

3.2.1.5 Boot interfaces

In the next sections, the configuration of the following boot devices is described:

- eMMC
- QSPI NOR flash
- SD card

¹⁰: Recommended settings.



3.2.1.6 Boot device eMMC

Table 7: Boot configuration eMMC at USDHC2

Signal / eFuse	Pin name	Ball	Setting	Default	TQMa6ULx ¹¹
BOOT_CFG1[7]	LCD_DATA07	D11	Boot Device Selection: 01 = Boot from USDHC Interface	0	0
BOOT_CFG1[6]	LCD_DATA06	A10		0	1
BOOT_CFG1[5]	LCD_DATA05	B10	SD/MMC Selection: 0 = SD/eSD/SDXC 1 = MMC/eMMC	0	1
BOOT_CFG1[4]	LCD_DATA04	C10	Fast Boot: 0 = Regular 1 = Fast boot	0	0
BOOT_CFG1[3]	LCD_DATA03	D10	MMC Speed: 0x = Normal Speed Mode 1x = High Speed Mode	0	0
BOOT_CFG1[2]	LCD_DATA02	E10		0	0
BOOT_CFG1[1]	LCD_DATA01	A9	eMMC Reset Enable: 0 = No action 1 = eMMC reset enabled (SD_RST pad)	0	0
BOOT_CFG1[0]	LCD_DATA00	B9	SD Loopback Clock Source Selection: 0 = through SD pad 1 = direct	0	0
BOOT_CFG2[7]	LCD_DATA15	D13	eMMC Bus Width: 000 = 1-bit 001 = 4-bit 010 = 8-bit 101 = 4-bit DDR (MMC 4.4) 110 = 8-bit DDR (MMC 4.4)	0	0
BOOT_CFG2[6]	LCD_DATA14	A12		0	0
BOOT_CFG2[5]	LCD_DATA13	B12		0	0
BOOT_CFG2[4]	LCD_DATA12	C12		0	0
BOOT_CFG2[3]	LCD_DATA11	D12	Port Select: 00 = USDHC1 01 = USDHC2	0	1
BOOT_CFG2[2]	LCD_DATA10	E12	Boot Frequencies (ARM / DDR): 0 = 500 / 400 MHz 1 = 250 / 200 MHz	0	0
BOOT_CFG2[1]	LCD_DATA09	A11	USDHC2 Voltage Selection: 0 = 3.3 V 1 = 1.8 V	0	0

In addition to the mode listed above the following eMMC modes are supported at port USDHC:

Table 8: USDHC2 mode eMMC

eMMC mode	1 bit	4 bit	8 bit	8 bit DDR
Normal speed	×	×	×	×
High speed	×	×	×	×

11: Recommended settings.



3.2.1.7 Boot device QSPI NOR flash

Table 9: Boot configuration QSPI NOR flash at QSPI1

Signal / eFuse	Pin name	Ball	Setting	Default	TQMa6ULx ¹²
BOOT_CFG1[7]	LCD_DATA07	D11	Boot Device Selection: 0001 = Boot from QuadSPI	0	0
BOOT_CFG1[6]	LCD_DATA06	A10		0	0
BOOT_CFG1[5]	LCD_DATA05	B10		0	0
BOOT_CFG1[4]	LCD_DATA04	C10		0	1
BOOT_CFG1[3]	LCD_DATA03	D10	QuadSPI Interface Selection: 0 = QSPI1 1 = Reserved	0	0
BOOT_CFG1[2]	LCD_DATA02	E10	DDRSMP: 000 = Default	0	0
BOOT_CFG1[1]	LCD_DATA01	A9		0	0
BOOT_CFG1[0]	LCD_DATA00	B9		0	0

12: Recommended settings.



3.2.1.8 Boot device SD card

Table 10: Boot configuration SD card at USDHC1

Signal / eFuse	Pin name	Ball	Setting	Default	TQMa6ULx ¹³
BOOT_CFG1[7]	LCD_DATA07	D11	Boot Device Selection: 01 = Boot from USDHC Interface	0	0
BOOT_CFG1[6]	LCD_DATA06	A10		0	1
BOOT_CFG1[5]	LCD_DATA05	B10	SD/MMC Selection: 0 = SD/eSD/SDXC 1 = MMC/eMMC	0	0
BOOT_CFG1[4]	LCD_DATA04	C10	Fast Boot: 0 = Regular 1 = Fast boot	0	0
BOOT_CFG1[3]	LCD_DATA03	D10	SD Speed: 00 = Normal/SDR12 01 = High/SDR25 10 = SDR50 11 = SDR104	0	0
BOOT_CFG1[2]	LCD_DATA02	E10		0	1
BOOT_CFG1[1]	LCD_DATA01	A9	SD Power Cycle Enable: 0 = No power cycle 1 = Enable via USDHC_RST pad	0	0
BOOT_CFG1[0]	LCD_DATA00	B9	SD Loopback Clock Source Sel: 0 = through SD pad 1 = direct	0	0
BOOT_CFG2[7]	LCD_DATA15	D13	SD Calibration Step: 00 = 1 delay cells 01 = 1 delay cells 10 = 2 delay cells 11 = 3 delay cells	0	0
BOOT_CFG2[6]	LCD_DATA14	A12		0	1
BOOT_CFG2[5]	LCD_DATA13	B12	Bus Width: 0 = 1-bit 1 = 4-bit	0	0
BOOT_CFG2[4]	LCD_DATA12	C12	Port Select: 00 = USDHC1 01 = USDHC2	0	0
BOOT_CFG2[3]	LCD_DATA11	D12		0	0
BOOT_CFG2[2]	LCD_DATA10	E12	Boot Frequencies (ARM / DDR): 0 = 500 / 400 MHz 1 = 250 / 200 MHz	0	0
BOOT_CFG2[1]	LCD_DATA09	A11	USDHC Voltage Selection: 0 = 3.3 V 1 = 1.8 V	0	0

In addition to the mode listed above the following SD card modes are supported at port USDHC1:

Table 11: USDHC1 SD card modes

SD mode	Fast boot	1 bit	4 bit
Normal speed	×	×	×
High speed	×	×	×
SDR50	–	–	–
SDR104	–	–	–

13: Recommended settings.

3.2.2 Memory

3.2.2.1 DDR3L SDRAM

One DDR3L SDRAM chip is assembled on the TQMa6ULx. The chip is connected to the CPU with a bus width of 16 bit. The following block diagram shows how the DDR3L SDRAM is connected to the processor.

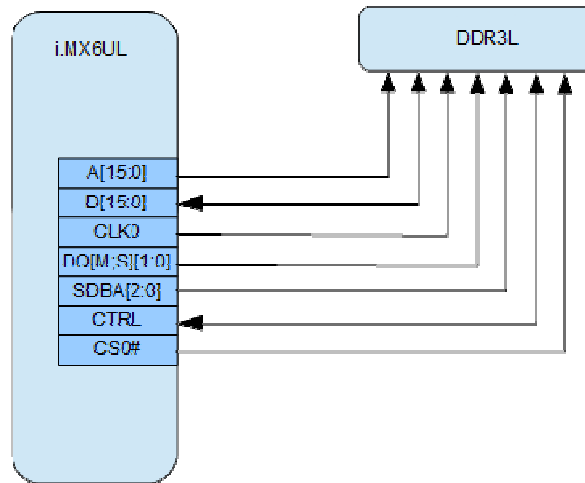


Illustration 3: Block diagram DDR3L SDRAM interface

The characteristics of the memory interface are shown in the following table:

Table 12: i.MX6ULx SDRAM interface

CPU derivative	Bus width	Frequency	No. of SDRAM chips	TQ-BSP support
i.MX6ULx	× 16	400 MHz	1	X

The assembly options of DDR3L SDRAM on the TQMa6ULx are listed in the following table:

Table 13: DDR3L SDRAM

Manufacturer	Part number	Type	Temperature range
Micron	MT41K128M16JT-125 IT:K	DDR3L-1600 128M16	-40 °C to +95 °C
Samsung	K4B2G1646F-BMK0	DDR3L-1600 128M16	-40 °C to +95 °C

3.2.2.2 eMMC NAND flash

An eMMC NAND flash is provided for the boot loader and the application software. The following block diagram shows how the eMMC flash is connected to the processor.

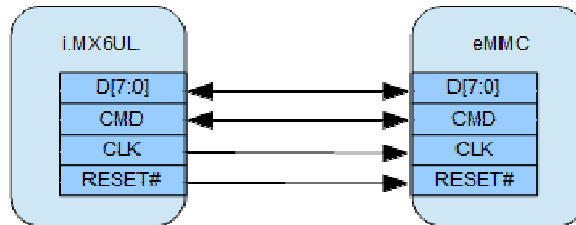


Illustration 4: Block diagram eMMC interface

It depends on the BSP implementation, whether the Hardware Reset-Function is supported. The following table shows the eMMC devices, which can be assembled on the TQMa6ULx:

Table 14: eMMC NAND flash

Manufacturer	Part number	Type	Temperature range
Micron	MTFC4GACAJCN-1M-WT	4 GByte / 4.41 / MLC / 25 nm	-25 °C to +85 °C
Micron	MTFC4GACAJCN-4M-IT	4 GByte / 5.0 / MLC / 20 nm	-40 °C to +85 °C

3.2.2.3 QSPI NOR flash

A QSPI NOR flash is also available. It can e.g., serve as boot device or as recovery device. The following block diagram shows how the QSPI NOR flash is connected to the processor.

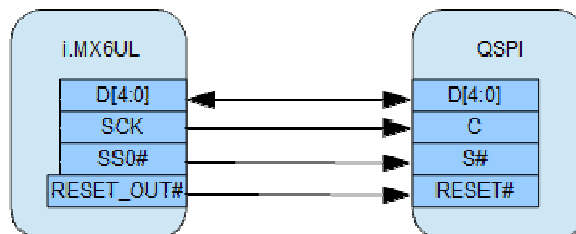



Illustration 5: Block diagram QSPI NOR flash interface

The Reset-Out pin of the QSPI NOR flash as well as the QSPI lines are routed to the connectors of the TQMa6ULx. The following table shows the QSPI NOR flash devices, which can be assembled on the TQMa6ULx:

Table 15: QSPI NOR flash

Manufacturer	Part number	Size		Temperature range
Micron	N25Q256A13E1240F	256 Mbit	32 Mbyte	-40 °C to +85 °C
Micron	MT25QL512ABB8E12-0SIT	512 Mbit	64 Mbyte	-40 °C to +85 °C
Micron	MT25QL02GCB8E12-0SIT	2 Gbit	256 Mbyte	-40 °C to +85 °C

Attention: QSPI-Mode



For the Quad-Mode-Boot it is essential, to set the Quad-Enable-Bit in the QSPI flash before the boot process starts.

3.2.2.4 EEPROM

A serial EEPROM for permanent storage of e.g. module characteristics or customers parameters is available as assembly option. The I2C4 bus of the processor controls the EEPROM. Write-Protection (WP) is not supported by default but available as an assembly option.

The following block diagram shows how the EEPROM is connected to the processor.

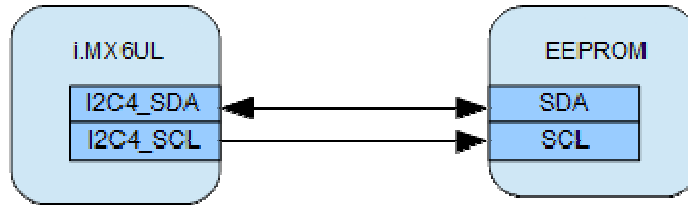


Illustration 6: Block diagram EEPROM interface

The following table shows details of the EEPROM:

Table 16: EEPROM

Manufacturer	Part number	Type	Temperature range
STM	M24C64-RDW6TP	64 Kbit	-45 °C to +85 °C

- The I²C address of the EEPROM is 0x50 / 0b1010000

In the EEPROM, module-specific data is stored. It is, however, not essential for the correct operation of the TQMa6ULx. The user can delete or alter the data.

In the following table, the parameters stored in the EEPROM are shown:

Table 17: TQMa6ULx specific data in the EEPROM

Offset	Payload (byte)	Padding (byte)	Size (byte)	Type	Remark
0x00	Variable	Variable	32 ₍₁₀₎	Binary	Hard Reset Configuration Word (HRCW), (optional)
0x20	6 ₍₁₀₎	10 ₍₁₀₎	16 ₍₁₀₎	Binary	MAC address
0x30	8 ₍₁₀₎	8 ₍₁₀₎	16 ₍₁₀₎	ASCII	Serial number
0x40	Variable	Variable	64 ₍₁₀₎	ASCII	Order code
0x80	–	–	8,064 ₍₁₀₎	–	(Unused)

3.2.3 RTC

The i.MX6ULx provides an RTC, which has its own power domain (SNVS). The accuracy of the RTC is mainly determined by the characteristics of the quartz used. The type FC-135 used on the TQMa6ULx has a standard frequency tolerance of ± 20 ppm @ +25 °C. (Parabolic coefficient: max. $-0.04 \times 10^{-6} / ^\circ\text{C}^2$).

The following block diagram shows the implementation on the TQMa6ULx.

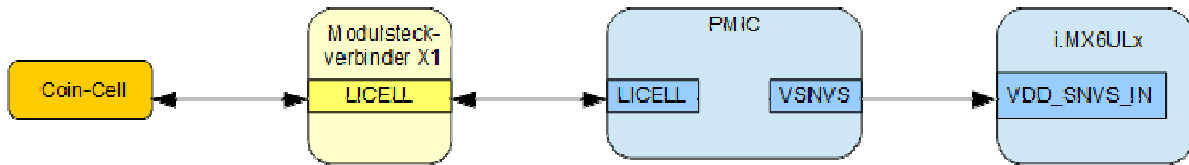



Illustration 7: Block diagram RTC

The RTC power domain SNVS of the CPU is supplied by the PMIC-internal regulator VSNVS. This regulator is supplied either by VIN or by LICELL. LICELL supports simple coin cells as well as Lithium coin cells or SuperCaps, which can also be charged by the PMIC. Charging methods and electrical characteristics of the pin LICELL are to be taken from the Data Sheet of the PMIC (7).

Attention: Power consumption of RTC



A coin cell is not suitable for long term bridging because of the high current consumption. A Lithium coin cell or a SuperCap might be an option depending on the use case. It is to be taken note of that the typical charging current is only 60 μA .
For long term bridging an external RTC connected at the I²C bus on the carrier board is recommended.

3.2.4 Temperature sensor

A temperature sensor for temperature supervision of the TQMa6ULx is provided.

It is placed on the bottom side of the TQMa6ULx, (D2 in Illustration 18).

The following block diagram shows how the temperature sensor is connected to the processor.

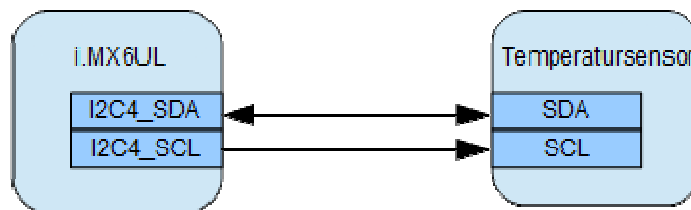


Illustration 8: Block diagram temperature sensor interface

The "OS"-output (over-temperature shutdown) of the sensor is not connected.

The following table shows details of the temperature sensor:

Table 18: Temperature sensor

Manufacturer	Part number	Resolution	Error	Temp. range
NXP	LM75ADP	11 bit ADC	Max. ± 3 °C	-55 °C to +125 °C

- The I²C address of the temperature sensor is 0x48 / 0b1001000



3.2.5 Interfaces

3.2.5.1 Overview

The TQMa6ULx provides interfaces with primary functions. They can all be used simultaneously independent of their configuration. Some of the primary functions are not available if a secondary function is used:

Table 19: Internal interfaces

Interface	Number	Function	Section	Remark
USDHC	1	Primary		USDHC2 eMMC, 8 data bits
MMDC	1	Primary		DDR3L-SDRAM, 16 data bits
QSPI	1	Primary		QSPI NOR flash, 4 data bits

Table 20: External interfaces

Interface	Number	Function	Section	Remark
CCM	2	Secondary		Multiplexing has to be adapted
CSI	1	Secondary		Multiplexing has to be adapted
ECSPI	1	Primary		ECSPI2
ECSPI	2	Secondary		ECPSI1 / ECSPi3 / ECSPi4 Multiplexing has to be adapted
EIM	1	Secondary		Multiplexing has to be adapted
ENET	2	Primary		RMIi (10/100 Mbit/s) / 1588 Multiplexing has to be adapted
EPIT	2	Secondary		Multiplexing has to be adapted
FLEXCAN	2	Primary		FLEXCAN[2:1]
GPIO	11	Primary		GPIO1 / GPIO4
GPT	2	Secondary		GPT[2:1] Multiplexing has to be adapted
I ² C	2	Primary		I2C2 / I2C4
I ² C	2	Secondary		I2C1 / I2C3 Multiplexing has to be adapted
KPP	1	Secondary		Multiplexing has to be adapted
LCDIF	1	Primary		Graphics interface
MQS	1	Secondary		Multiplexing has to be adapted
NAND	1	Secondary		Multiplexing has to be adapted
PWM	8	Secondary		PWM[8:1] Multiplexing has to be adapted
SAI	3	Secondary		SAI[3:1] Multiplexing has to be adapted
SIM	2	Secondary		Multiplexing has to be adapted
SJC	1	Primary		JTAG
SNVS	1	Primary		SNVS_TAMPER[9-0]
SRC	1	Secondary		Depends on BOOT_MODE0 BOOT_MODE1
SPDIF	1	Secondary		Multiplexing has to be adapted
UART	3	Primary		UART1 / UART3 / UART6
UART	5	Secondary		UART2 / UART4 / UART[8:7] Multiplexing has to be adapted
USB	2	Primary		USB_OTG1 / USB_OTG2
USDHC	1	Primary		SD card-Interface
WDOG	1	Secondary		WDOG[3:1] Multiplexing has to be adapted
XTALOSC	1	Primary		CCM_CLK1_N / CCM_CLK1_P

In the following sections, only the external primary interfaces are described.

3.2.5.2 ECSPi - Enhanced Configurable SPi

The i.MX6ULx provides four ECSPi interfaces, which are all full-duplex and can be configured as Master/Slave.

Primarily ECSPi2 is available at the connectors of the TQMa6ULx.

The following table shows the signals used by the ECSPi2 interface:

Table 21: Signals ECSPi2

Signal name	Direction	Pin	Remark
ECSPi2_MISO	I		
ECSPi2_MOSI	O		
ECSPi2_SCLK	O		
ECSPi2_SS0	O		

3.2.5.3 ENET – Fast Ethernet

The i.MX6ULx provides a 10/100 MAC core, which supports MII (4 bit) and RMII (2 bit).

The RGMII signals are available as primary function at the connectors of the TQMa6ULx.

The following table shows the signals used by the RMII interface:

Table 22: Signals RMII

Signal name	Power-Group	Direction	Pin	Remark
ENET_MDC	NVCC_GPIO (3.3 V)	O		
ENET_MDIO		I/O		
ENET1_RDATA[1:0]	NVCC_ENET (2.5 V / 3.3 V)	I		
ENET1_RX_EN		I		
ENET1_RX_ER		I		
ENET1_TDATA[1:0]		O		
ENET1_TX_CLK		O		
ENET1_TX_EN		O		
ENET2_RDATA[1:0]		I		
ENET2_RX_EN		I		
ENET2_RX_ER		I		
ENET2_TDATA[1:0]		O		
ENET2_TX_CLK		O		
ENET2_TX_EN		O		

Attention: NVCC_ENET



NVCC_ENET has to be connected externally!

The RMII interface of the i.MX6ULx works with an I/O voltage of 2.5 V or 3.3 V. In order to use the interface, additional signals of the signal group ENET are required. The accompanying power supply pin is routed to the connector to operate these signals on the same I/O voltage, if RMII is used.

By adapting the multiplexing, it is possible to use MII. Details are to be taken from the Reference Manual and the Data Sheet of the CPU (1), (6).

- VCC3V3_REF_OUT or VCC3V3_V33_OUT can be used as I/O supply voltage for an RMII-PHY.

3.2.5.4 CAN – FLEXCAN

The i.MX6ULx provides two integrated CAN 2.0B controllers. Both signals pairs are available at the connectors of the TQMa6ULx. The drivers required have to be implemented on the carrier board.

The following table shows the signals used by the CAN interface:

Table 23: Signals FLEXCAN

Signal name	Direction	Pin	Remark
FLEXCAN1_RX	I		
FLEXCAN1_TX	O		
FLEXCAN2_RX	I		
FLEXCAN2_TX	O		

3.2.5.5 GPIO

Beside their interface function, most of the pins of the i.MX6ULx can also be configured as GPIO.

All these GPIOs can trigger an interrupt. Details are to be taken from the Reference Manual and the Data Sheet of the CPU (1), (6). In addition, different pins are already marked as GPIO and are available on the connectors of the TQMa6ULx.

The following table shows the GPIO signals provided:

Table 24: Signals GPIO

Signal name	Remark	Direction	Pin	Remark
GPIO1_IO09		I/O		
GPIO1_IO18		I/O		
GPIO1_IO19		I/O		
GPIO4_IO21	NVCC_CSI (1.8 V / 3.3 V)	I/O		
GPIO4_IO22		I/O		
GPIO4_IO23		I/O		
GPIO4_IO24		I/O		
GPIO4_IO25		I/O		
GPIO4_IO26		I/O		
GPIO4_IO27		I/O		
GPIO4_IO28		I/O		

Attention: NVCC_CSI



NVCC_CSI has to be connected externally!

The electrical characteristics of the GPIOs are to be taken from the Data Sheet of the CPU (1).

3.2.5.6 I²C

The i.MX6ULx provides four I²C interfaces.


I2C2 and I2C4 are routed to the connectors of the TQMa6ULx and are available as primary function.

The following table shows the signals used by the I²C interfaces:

Table 25: Signals I²C

Signal name	Remark	Direction	Pin	Remark
I2C2_SCL	NVCC_CSI (1.8 V / 3.3 V)	O		
I2C2_SDA		I/O		
I2C4_SCL	PU 2.2 kΩ to 3.3 V on TQMa6ULx	O		
I2C4_SDA		I/O		

Attention: NVCC_CSI

	NVCC_CSI has to be connected externally!
---	--

The following table shows the I²C devices connected to the I2C1 bus on the TQMa6ULx:

Table 26: I²C address assignment

Component	Address
EEPROM (M24C64)	0x50 / 0b1010000
Temperature sensor (LM75A)	0x48 / 0b1001000
PMIC (MC32PF3000A7EP)	0x08 / 0b0001000

If more devices are connected to the I²C buses on the carrier board, the maximum capacitive bus load according to the I²C standard has to be taken note of. If necessary, additional Pull-Ups at the bus should be provided on the carrier board.

3.2.5.7 eLCDIF – Enhanced LCD Interface

The i.MX6ULx CPU provides a display controller, which supports displays of different size and performance. Information regarding types of displays and supported formats are to be taken from the Reference Manual of the CPU (6).

The LCD signals routed to the connectors of the TQMa6ULx as primary function.

The following table shows the signals used by the LCD interface:

Table 27: Signals LCD

Signal name	Direction	Pin	Remark
LCDIF_CLK	O		
LCDIF_DATA[23:0]	I/O		
LCDIF_ENABLE	O		
LCDIF_HSYNC	O		
LCDIF_RESET	O		
LCDIF_VSYNC	O		



3.2.5.8 SJC – System JTAG Controller

The i.MX6ULx can operate in two different JTAG modes. The pin JTAG_MOD defines the mode.

The following table shows the existing modes as well as the mode set on the TQMa6ULx:

Table 28: JTAG modes

JTAG_MOD	Default	Name	Remark
0	X	Daisy Chain All	For common SW debug (High speed and series production)
1		SJC only	IEEE 1149.1 JTAG compliant mode

The following table shows the signals used by the JTAG interface:

Table 29: Signals JTAG

Signal name	Direction	Pin	Remark
JTAG_TCK	I		i.MX6ULx internal PU 47 kΩ
JTAG_TMS	I		i.MX6ULx internal PU 47 kΩ
JTAG_TDI	I		i.MX6ULx internal PU 47 kΩ
JTAG_TDO	O		i.MX6ULx internal keeper
JTAG_TRST#	I		i.MX6ULx internal PU 47 kΩ
JTAG_MOD	I		PD 4.7 kΩ on TQMa6ULx + i.MX6ULx-internal PU 100 kΩ

3.2.5.9 TAMPER

The i.MX6ULx provides protection against unauthorised opening or manipulation of a device by tamper detection.

The TAMPER pins are available for this purpose at the connectors of the TQMa6ULx.

The following table shows the available signals:

Table 30: Signals TAMPER

Signal name	Direction	Pin	Remark
SNVS_TAMPER[9:0]	I		

Details about the function of the TAMPER pins are to be taken from the Reference Manual of the CPU (6).

3.2.5.10 UART

The i.MX6ULx provides eight UART interfaces. UART2 to UART5 also offer handshake signals and are available at the connectors as primary function. No handshake signals are configured as primary function. More UARTs as well as handshake signals can be configured in the multiplexing. Details are to be taken from the Reference Manual of the CPU (6).

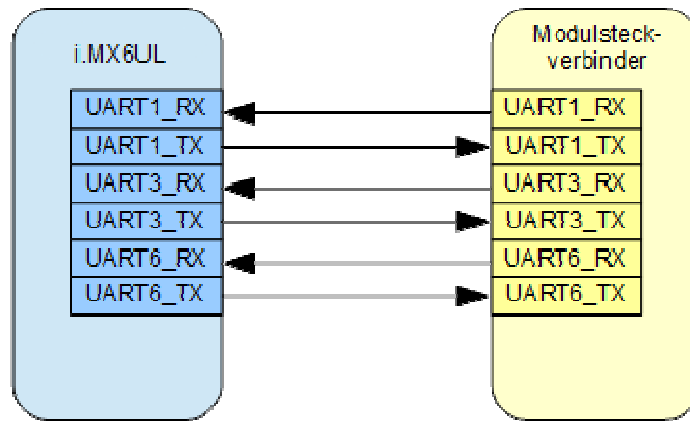


Illustration 9: Block diagram UART interfaces

The following table shows the signals used by the UART interfaces:

Table 31: Signals UART

Signal name	Direction	Pin	Remark
UART1_RX_DATA	I		
UART1_TX_DATA	O		
UART3_RX_DATA	I		
UART3_TX_DATA	O		
UART6_RX_DATA	I		
UART6_TX_DATA	O		

Note:

UART1 is configured as RS-232 on the MBa6ULx.



3.2.5.11 USB

The i.MX6ULx provides two independent USB-OTG controllers with integrated High-Speed PHY.

Both USB-OTG controllers can operate in Host or in Device mode.

They are both available at the connectors of the TQMa6ULx as primary function.

The following table shows the signals used by the USB_OTG interfaces:

Table 32: Signals USB_OTG

Signal name	Direction	Pin	Remark
USB_OTG1_ID	I		Device Mode: USB_OTG_ID signal is high, Host Mode : USB_OTG_ID signal is low
USB_OTG1_OC	I		
USB_OTG1_PWR	O		
USB_OTG1_VBUS	P		
USB_OTG1_DN	I/O		
USB_OTG1_DP	I/O		
USB_OTG2_ID	I		Device Mode: USB_OTG_ID signal is high, Host Mode : USB_OTG_ID signal is low
USB_OTG2_OC	I		
USB_OTG2_PWR	O		
USB_OTG2_VBUS	P		
USB_OTG2_DN	I/O		
USB_OTG2_DP	I/O		

3.2.5.12 USDHC – Ultra-Secured Digital Host Controller

The i.MX6ULx provides a USDHC controller, which is the interface between Host system and SD/SDIO/MMC cards.

To connect an MMC, SD, or SDIO card the USDHC1 port of the i.MX6ULx is routed to the connectors of the TQMa6ULx.

The following table shows the signals used by the USDHC interface:

Table 33: Signals USDHC1

Signal name	Direction	Pin	Remark
USDHC1_CLK	O		
USDHC1_CMD	I/O		
USDHC1_DATA[3:0]	I/O		

3.2.5.13 XTAL – differential clock

The i.MX6ULx provides a differential clock output, which is routed to the connectors of the TQMa6ULx.

The following table shows details of the XTAL signals:

Table 34: Signals XTAL

Signal name	Direction	Pin	Remark
CCM_CLK1_N	O		
CCM_CLK1_P	O		

3.2.6 Reset signals

Reset inputs or outputs are available at the connectors of the TQMa6ULx.
The following block diagram shows the wiring of the reset signals.

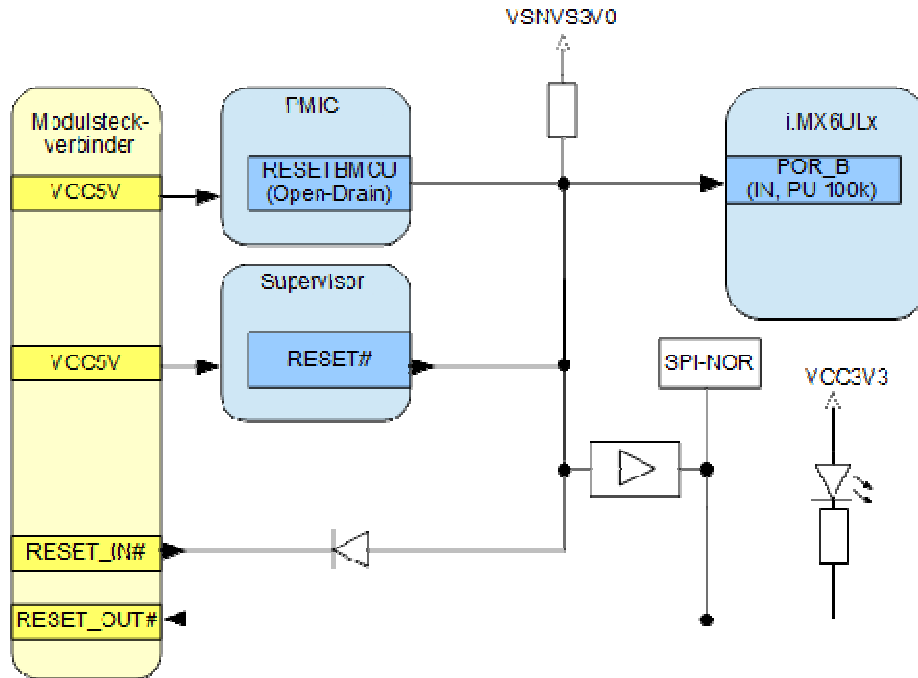


Illustration 10: Block diagram Reset

The following table describes the reset signals available at the connectors:

Table 35: Signals Reset

Signal name	Direction	Pin	Remark
RESET_IN#	I _{PU_100k}		<ul style="list-style-type: none"> Reset input POR_B (Power-On Reset) of the i.MX6ULx Generates COLD-Reset of the CPU Low-active signal Minimal duration to trigger a reliable Reset: app. 30 μs, see (6)
RESET_OUT#	O		<ul style="list-style-type: none"> Reset output RESETBMCU of the PMIC Can be used to reset external periphery

Other RESET# sources are:

- VIN – RESET#
- PMIC – RESETBMCU

A green LED on the TQMa6ULx indicates the RESET# condition.

3.2.7 Power supply

3.2.7.1 TQMa6ULx power supply

The following block diagram shows the power supply of the TQMa6ULx.

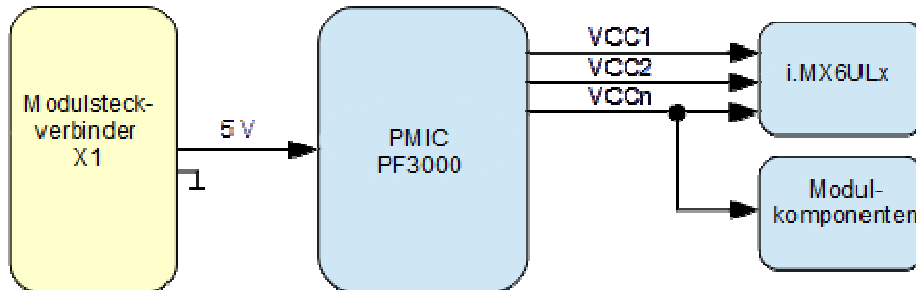


Illustration 11: Block diagram TQMa6ULx power supply

The characteristics and functions of the single pins and signals are to be taken from the Data Sheet of the PMIC (7) and the Reference Manual of the CPU (6).

3.2.7.2 TQMa6ULx power consumption

The given power consumption has to be seen as an approximate value. The power consumption of the TQMa6ULx strongly depends on the application, the mode of operation and the operating system.

The following table shows power supply and power consumption parameters of the TQMa6ULx:

Table 36: Parameter TQMa6ULx power consumption

Parameter	Value	Remark
Supply V_{IN}	5 V	$\pm 10\%$ - no other voltage is required
Current consumption U-Boot prompt	(TBD)	
Current consumption Linux prompt	(TBD)	
Current consumption Linux 100 % CPU load	(TBD)	

3.2.7.3 Voltage monitoring

The TQMa6ULx features a supervisor which monitors the input voltage (VCC5V).

If the input voltage is too low, a Reset is triggered until the input voltage is in the permitted range again.

The block diagram in Illustration 10 shows the wiring.

The Supervisor triggers typically at 4.55 V (min: 4.45 V / max: 4.65 V) and has a delay of 200 ms.


All other voltages generated on the TQMa6ULx are routed to the connectors and can be monitored on the carrier board.

3.2.7.4 Power-Up sequence TQMa6ULx / carrier board

The TQMa6ULx meets the required sequencing of the CPU (6) by using the PMIC (7).

The TQMa6ULx operates with 5 V, but the 3.3 V I/O voltage of the CPU signals is generated on the TQMa6ULx.

This leads to requirements for the carrier board design concerning the chronological characteristics of the voltages generated on the carrier board.

Attention: Power-Up sequence	
	<p>No I/O pins of the TQMa6ULx may be driven by external components during the boot-process to avoid cross-supply and errors in the power-up sequence.</p> <p>To ensure a correct Power-Up, the following sequence must be met on the carrier board:</p> <p>The supply voltage of 5 V for the TQMa6ULx is present and the carrier board supply of 3.3 V is activated by the module pin VCC3V3_REF_OUT (X1-17).</p>

The following block diagram shows the control of the voltage regulator on the carrier board:

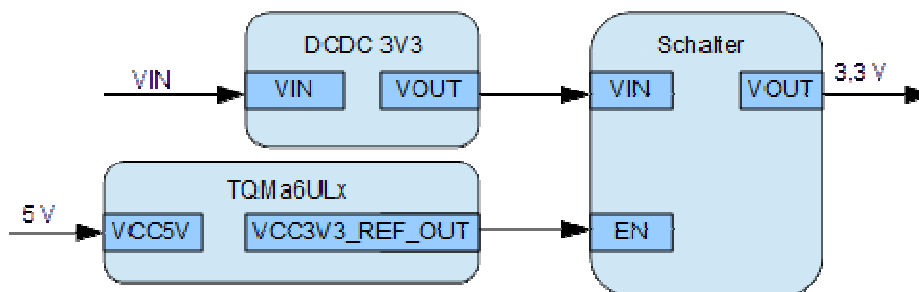


Illustration 12: Block diagram power supply carrier board

- The BOOT_MODE and BOOT_CFG pins have dedicated reference voltages, which are present at the right time.

3.2.7.5 Power modes

- System Idle
- Suspend to RAM (deep sleep mode - DSM)
- SNVS (RTC)

DSM und SNVS is an extremely efficient energy saving mode, in which parts of the core supply are switched off. This has to be supported by the software.

3.2.7.6 PMIC

The characteristics and functions of all pins and signals have to be taken from the Reference Manual of the CPU (6) and the Data Sheet of the PMIC (7). The PMIC is connected to the I2C4 bus of the i.MX6ULx.

The following block diagram shows the connection between PMIC and CPU:

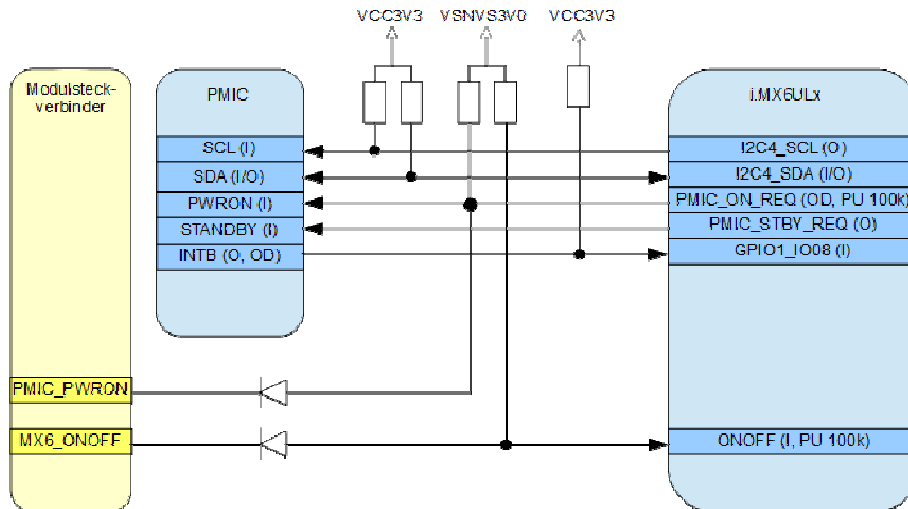


Illustration 13: Block diagram PMIC interface

4. MECHANICS

4.1 Connectors

The TQMa6ULx is connected to the carrier board with 200 pins on three connectors. The following table shows details of the plug connector:

Table 37: Plug connectors on the TQMa6ULx

Manufacturer	Part number	Remark
TE connectivity	100-pin: 5177985-4	0.8 mm pitch Plating: Gold 0.2 µm -40 °C to +125 °C

The TQMa6ULx is held in the plug connectors with a considerable retention force.

To avoid damaging the plug connectors of the TQMa6ULx as well as the plug connectors on the carrier board while removing the TQMa6ULx the use of an extraction tool is strongly recommended. See section 4.8 for further information.

The following table shows some suitable mating plug connectors for the carrier board.

Table 38: Suitable carrier board mating plug connectors

Manufacturer	Part number	Remark	Stack height (X)	
TE connectivity	100-pin: 5177986-4	On MBa6ULx	5 mm	
TE connectivity	100-pin: 1-5177986-4	-	6 mm	
TE connectivity	100-pin: 2-5177986-4	-	7 mm	
TE connectivity	100-pin: 3-5177986-4	-	8 mm	

The pins assignment listed in Table 2 and Table 3 refer to the corresponding standard BSP of TQ-Systems GmbH. Information regarding I/Os in Table 2 and Table 3 refer to the CPU pins.



4.2 Dimensions

Illustration 14: Height of TQMa6ULx

Illustration 15: Overall dimensions (top view)

Illustration 16: Top view through PCB

4.4 Adaptation to the environment

The overall dimensions (length × width × height) of the TQMa6ULx are 46 × 32 × 7.4 mm³.
The maximum height of the TQMa6ULx above the carrier board is approximately 8.4 mm.

4.5 Protection against external effects

As an embedded module, the TQMa6ULx is not protected against dust, external impact and contact (IP00). Adequate protection has to be guaranteed by the surrounding system.

4.6 Thermal management

To cool the TQMa6ULx, a theoretical maximum of approximately (TBD) have to be dissipated.
The power dissipation originates primarily in the CPU, the DDR3L SDRAM and the PMIC.
The power dissipation also depends on the software used and can vary according to the application.
See NXP documents (3) and (7) for further information.

Attention: Destruction or malfunction



The CPU belongs to a performance category in which a cooling system may be essential in certain applications. It is the responsibility of the customer to define a suitable cooling method depending on the specific mode of operation (e.g., dependence on clock frequency, stack height, airflow, and software).

4.7 Structural requirements

The TQMa6ULx is held in the mating plug connectors by the retention force of the pins (200). For high requirements with respect to vibration and shock firmness, an additional holder has to be provided in the final product to hold the TQMa6ULx in its position. For this purpose, TQ-Systems GmbH can provide a suitable solution. As no heavy and big components are assembled, no further requirements are given.

4.8 Notes of treatment

To avoid damage caused by mechanical stress, the TQMa6ULx may only be extracted from the carrier board by using the extraction tool MOZIA6ULx that can also be obtained separately.

Attention: Note with respect to the component placement of the carrier board



2.5 mm should be kept free on the carrier board, along the longitudinal edges on both sides of the TQMa6ULx for the extraction tool.

5. SOFTWARE

The TQMa6ULx is delivered with a preinstalled boot loader U-Boot and a TQ-BSP, which is configured for the MBa6ULx. The boot loader U-Boot provides module-specific as well as board-specific settings, e.g.:

- CPU configuration
- PMIC configuration
- SDRAM configuration
- eMMC configuration
- Multiplexing
- Clocks
- Pin configuration
- Driver strengths

More information can be found in the [Support Wiki for the TQMa6ULx](#).



6. SAFETY REQUIREMENTS AND PROTECTIVE REGULATIONS

6.1 EMC

The TQMa6ULx was developed according to the requirements of electromagnetic compatibility (EMC). Depending on the target system, anti-interference measures may still be necessary to guarantee the adherence to the limits for the overall system.

Following measures are recommended:

- Robust ground planes (adequate ground planes) on the printed circuit board
- A sufficient number of blocking capacitors in all supply voltages
- Fast or permanent clocked lines (e.g., clock) should be kept short; avoid interference of other signals by distance and / or shielding besides, take note of not only the frequency, but also the signal rise times
- Filtering of all signals, which can be connected externally (also "slow signals" and DC can radiate RF indirectly)

Since the TQMa6ULx operates on an application-specific carrier board, EMC or ESD tests only make sense for the whole device. The TQMa6ULx is designed to pass the following test:

- EMC-Interference radiation:
Measurement of the electrically radiated emission for standard, residential, commercial and light industrial environments in the range of 30 MHz to 6 GHz according to DIN EN 55022 A1:2007.

6.2 ESD

In order to avoid interspersions on the signal path from the input to the protection circuit in the system, the protection against electrostatic discharge should be arranged directly at the inputs of a system. As these measures always have to be implemented on the carrier board, no special preventive measures were planned on the TQMa6ULx.

Following measures are recommended for a carrier board:

- Generally applicable: Shielding of the inputs (shielding connected well to ground / housing on both ends)
- Supply voltages: Protection by suppressor diode(s)
- Slow signal lines: RC filtering, perhaps Zener diode(s)
- Fast signal lines: Integrated protective devices (e.g., suppressor diode arrays)

6.3 Operational safety and personal security

Due to the occurring voltages (≤ 5 V DC), tests with respect to the operational and personal safety have not been carried out.



6.4 Climatic and operational conditions

The possible temperature range strongly depends on the installation situation (heat dissipation by heat conduction and convection); hence, no fixed value can be given for the whole assembly.

In general, a reliable operation is given when following conditions are met:

Table 39: Climate and operational conditions extended temperature range –25 °C to +85 °C

Parameter	Range	Remark
Chip temperature CPU i.MX6ULx	–40 °C to +105 °C	Typical max +90 °C
Environment temperature CPU i.MX6ULx	–40 °C to +85 °C	–
Chip temperature PMIC	–40 °C to +125 °C	–
Environment temperature PMIC	–40 °C to +85 °C	–
Package temperature DDR3L-SDRAM	–40 °C to +85 °C	–
Package temperature other ICs	–25 °C to +85 °C	–
Permitted storage temperature TQMa6ULx	–40 °C to +85 °C	–
Relative humidity (operating / storage)	10 % to 90 %	Not condensing

Table 40: Climate and operational conditions industrial temperature range –40 °C to +85 °C

Parameter	Range	Remark
Chip temperature CPU i.MX6ULx	–40 °C to +105 °C	Typical max +90 °C
Environment temperature CPU i.MX6ULx	–40 °C to +85 °C	–
Chip temperature PMIC	–40 °C to +125 °C	–
Environment temperature PMIC	–40 °C to +85 °C	–
Package temperature DDR3L-SDRAM	–40 °C to +85 °C	–
Package temperature other ICs	–40 °C to +85 °C	–
Permitted storage temperature TQMa6ULx	–40 °C to +85 °C	–
Relative humidity (operating / storage)	10 % to 90 %	Not condensing

Detailed information concerning the thermal characteristics of the CPU is to be taken from the NXP documents (3) and (7).



6.5 Shock and Vibration

Table 41: Shock resistance

Parameter	Details
Shocks	According to DIN EN 60068-2-27
Shock form	Half sine
Acceleration	30 g
Residence time	10 ms
Number of shocks	3 shocks per direction
Excitation axes	6X, 6Y, 6Z

Table 42: Vibration resistance

Parameter	Details
Oscillation, sinusoidal	According to DIN EN 60068-2-6
Frequency ranges	2 – 9 Hz, 9 – 200 Hz, 200 – 500 Hz
Wobble rate	1.0 octaves / min
Excitation axes	X– Y – Z axis
Amplitude	2 Hz ... 9 Hz: 3.5 ms ⁻² 9 Hz ... 200 Hz: 10 ms ⁻² 200 Hz ... 500 Hz: 15 ms ⁻²

6.6 Reliability and service life

The theoretical MTBF at a constant error rate is approximately (TBD) @ +40 °C for the TQMa6ULx.

The TQMa6ULx is designed to be insensitive to shock and vibration.

Connectors, which guarantee at least 100 mating cycles, are assembled on the TQMa6ULx.

Detailed information concerning the service life of the CPU under different operational conditions is to be taken from the NXP Application Note (4).



7. ENVIRONMENT PROTECTION

7.1 RoHS

The TQMa6ULx is manufactured RoHS compliant.

- All components and assemblies are RoHS compliant
- The soldering processes are RoHS compliant

7.2 WEEE

The company placing the product on the market is responsible for the observance of the WEEE regulation.

To be able to reuse the product, it is produced in such a way (a modular construction) that it can be easily repaired and disassembled.

7.3 REACH

The EU-chemical regulation 1907/2006 (REACH regulation) stands for registration, evaluation, certification and restriction of substances SVHC (Substances of very high concern, e.g., carcinogen, mutagen and/or persistent, bio accumulative and toxic). Within the scope of this juridical liability, TQ-Systems GmbH meets the information duty within the supply chain with regard to the SVHC substances, insofar as suppliers inform TQ-Systems GmbH accordingly.

7.4 EuP

The guideline 2005/32/EC (EuP) is the next step after WEEE® and RoHS for an environmentally friendly production of electric and electronic products. The consideration of environmental requirements with the product design "creation appropriate for the environment" ("ecological design") with the aim to improve the environmental compatibility of the product during its whole life cycle should be taken into consideration. The guideline appropriate for the product (embedded PC) is applied.

7.5 Battery

No batteries are assembled on the TQMa6ULx.

7.6 Packaging

By environmentally friendly processes, production equipment and products, we contribute to the protection of our environment. To be able to reuse the TQMa6ULx, it is produced in such a way (a modular construction) that it can be easily repaired and disassembled. The energy consumption of this subassembly is minimised by suitable measures. The TQMa6ULx is delivered in reusable packaging.

7.7 Other entries

The energy consumption of this subassembly is minimised by suitable measures.

Because currently there is still no technical equivalent alternative for printed circuit boards with bromine-containing flame protection (FR-4 material), such printed circuit boards are still used.

No use of PCB containing capacitors and transformers (polychlorinated biphenyls).

These points are an essential part of the following laws:

- The law to encourage the circular flow economy and assurance of the environmentally acceptable removal of waste as at 27.9.94 (Source of information: BGBl I 1994, 2705)
- Regulation with respect to the utilization and proof of removal as at 1.9.96 (Source of information: BGBl I 1996, 1382, 1997, 2860)
- Regulation with respect to the avoidance and utilization of packaging waste as at 21.8.98 (Source of information: BGBl I 1998, 2379)
- Regulation with respect to the European Waste Directory as at 1.12.01 (Source of information: BGBl I 2001, 3379)

This information is to be seen as notes. Tests or certifications were not carried out in this respect.



8. APPENDIX

8.1 Acronyms and definitions

The following acronyms and abbreviations are used in this document:

Table 43: Acronyms

Acronym	Meaning

8.2 References

Table 44: Further applicable documents

No.	Name	Rev., Date	Company
(1)	i.MX 6UltraLite Applications Processors for Industrial Products IMX6ULxIEC_rev1.pdf	Rev. 1, 04/2016	NXP
(2)	Chip Errata for the i.MX 6UltraLite IMX6ULxCE_rev1.pdf	Rev. 1, 04/2016	NXP
(3)	i.MX 6UltraLite Power Consumption Measurement AN5170_power_rev2.pdf	Rev. 2, 05/2016	NXP
(4)	i.MX 6UltraLite Product Usage Lifetime Estimates AN5198_life_rev1.pdf	Rev. 1, 04/2016	NXP
(5)	Hardware Development Guide for the i.MX 6UltraLite Applications Processor IMX6ULxHDG_rev1.pdf	Rev. 1, 03/2016	NXP
(6)	i.MX 6UltraLite Applications Processor Reference Manual IMX6ULxRM_rev1.pdf	Rev. 1, 04/2016	NXP
(7)	Power management integrated circuit (PMIC) for i.MX7 & i.MX 6SL/SX/UL	Rev. 7, 03/2016	NXP
(8)	MBa6ULx Preliminary User's Manual	– current –	TQ-Systems
(9)	Support-Wiki for the TQMa6ULx	– current –	TQ-Systems
(10)			

